

Statistical Data Analysis 2021/22

Lecture Week 2



London Postgraduate Lectures on Particle Physics
University of London MSc/MSci course PH4515



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Course web page via RHUL moodle (PH4515) and also
`www.pp.rhul.ac.uk/~cowan/stat_course.html`

Statistical Data Analysis

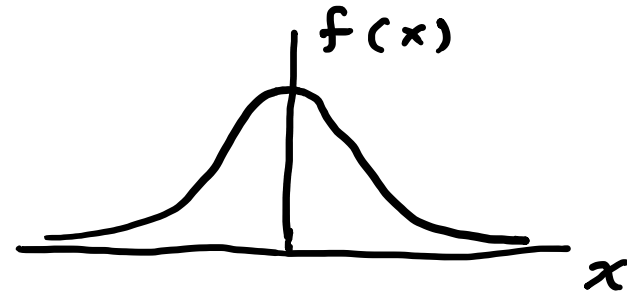
Lecture 2-1

- Functions of random variables
 - Single variable, unique inverse
 - Function without unique inverse
 - Functions of several random variables

Functions of a random variable

A function of a random variable *is itself* a random variable.

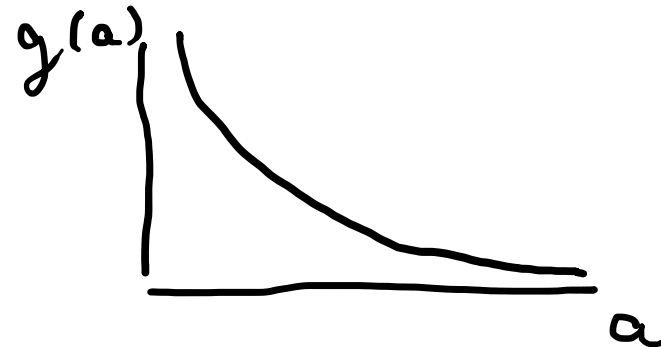
Suppose x follows a pdf $f(x)$



Consider a function $a(x)$

e.g. $a = x^2$

What is the pdf $g(a)$?

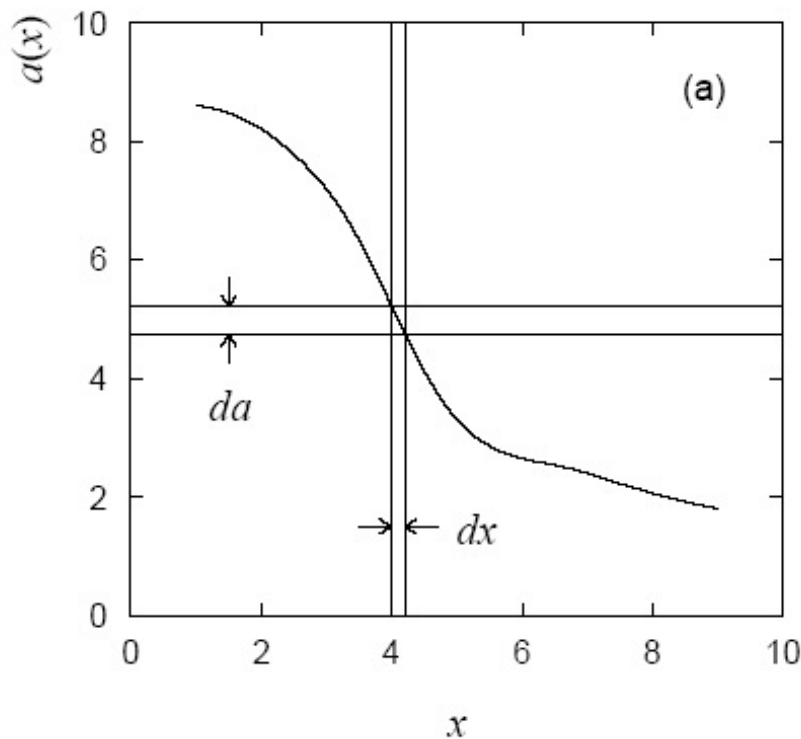


Function of a single random variable

General prescription:

$$g(a) da = \int_{dS} f(x) dx$$

dS = region of x space for which a is in $[a, a+da]$.



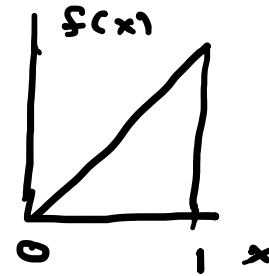
For one-variable case with unique inverse this is simply

$$g(a) da = f(x) dx$$

$$\rightarrow g(a) = f(x(a)) \left| \frac{dx}{da} \right|$$

Example: function with unique inverse

$$f(x) = 2x, \quad 0 < x \leq 1$$



$$a = -\ln x$$

$$x = e^{-a}, \quad \frac{dx}{da} = -e^{-a}$$

$$g(a) = f(x(a)) \left| \frac{dx}{da} \right| = 2e^{-a} \cdot |-e^{-a}|$$

$$= 2e^{-2a}$$

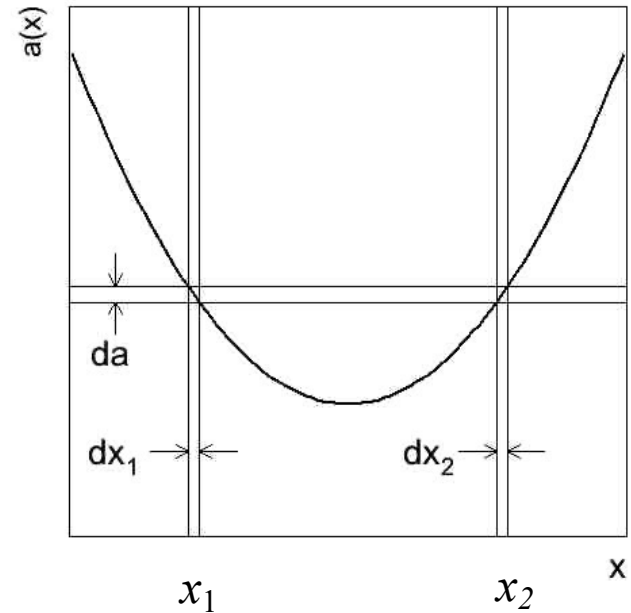
$$0 \leq a < \infty$$



Functions without unique inverse

If inverse of $a(x)$ not unique,
include all dx intervals in dS
which correspond to da :

$$g(a) = \sum_i f(x_i(a)) \left| \frac{dx}{da} \right|_{x_i(a)}$$



Example: $a(x) = x^2$, $x_1(a) = -\sqrt{a}$, $x_2(a) = \sqrt{a}$, $\frac{dx_{1,2}}{da} = \mp \frac{1}{2\sqrt{a}}$

$$dS = [x_1, x_1 + dx_1] \cup [x_2, x_2 + dx_2]$$

$$g(a) = f(x_1(a)) \left| \frac{dx}{da} \right|_{x_1(a)} + f(x_2(a)) \left| \frac{dx}{da} \right|_{x_2(a)} = \frac{f(-\sqrt{a})}{2\sqrt{a}} + \frac{f(\sqrt{a})}{2\sqrt{a}}$$

Change of variable example (cont.)

Suppose the pdf of x is $f(x) = \frac{x+1}{2}$, $-1 \leq x \leq 1$

and we consider the function $a(x) = x^2$ (so $0 \leq a \leq 1$)

and the inverse has two parts: $x = \pm\sqrt{a}$

To get the pdf of a we include the contributions from both parts:

$$g(a) = \frac{-\sqrt{a}+1}{2 \cdot 2\sqrt{a}} + \frac{\sqrt{a}+1}{2 \cdot 2\sqrt{a}} = \frac{1}{2\sqrt{a}}, \quad 0 \leq a \leq 1$$

Functions of more than one random variable

Consider a vector r.v. $\mathbf{x} = (x_1, \dots, x_n)$ that follows $f(x_1, \dots, x_n)$ and consider a scalar function $a(\mathbf{x})$.

The pdf of a is found from

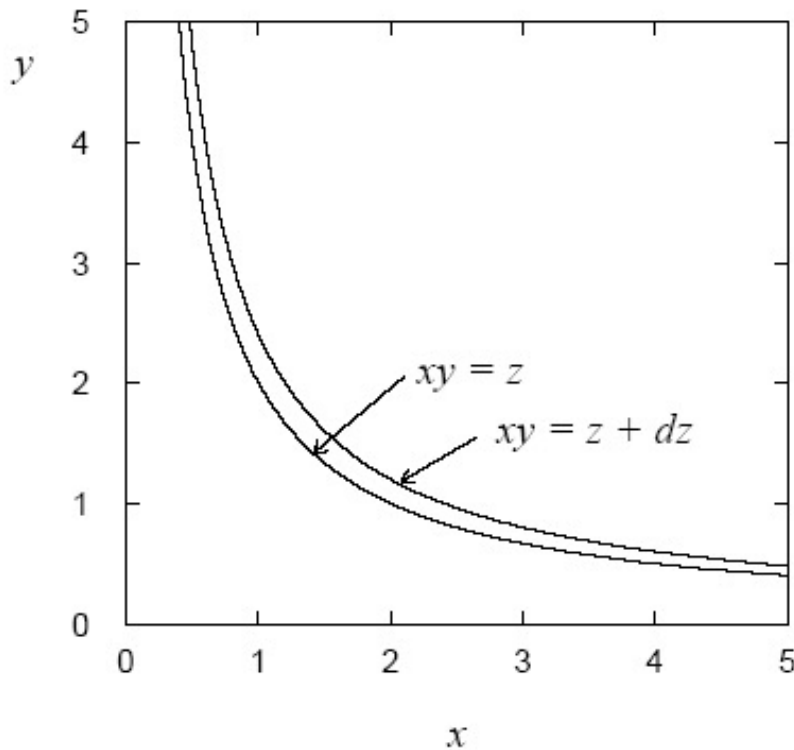
$$g(a')da' = \int \dots \int_{dS} f(x_1, \dots, x_n) dx_1 \dots dx_n$$

dS = region of \mathbf{x} -space between (hyper)surfaces defined by

$$a(\vec{x}) = a', \quad a(\vec{x}) = a' + da'$$

Functions of more than one r.v. (2)

Example: r.v.s $x, y > 0$ follow joint pdf $f(x, y)$,
consider the function $z = xy$. What is $g(z)$?



$$\begin{aligned} g(z) dz &= \int \dots \int_{dS} f(x, y) dx dy \\ &= \int_0^\infty dx \int_{z/x}^{(z+dz)/x} f(x, y) dy \\ \rightarrow g(z) &= \int_0^\infty f\left(x, \frac{z}{x}\right) \frac{dx}{x} \\ &= \int_0^\infty f\left(\frac{z}{y}, y\right) \frac{dy}{y} \end{aligned}$$

(Mellin convolution)

More on transformation of variables

Consider a random vector $\vec{x} = (x_1, \dots, x_n)$ with joint pdf $f(\vec{x})$.

Form n linearly independent functions $\vec{y}(\vec{x}) = (y_1(\vec{x}), \dots, y_n(\vec{x}))$
for which the inverse functions $x_1(\vec{y}), \dots, x_n(\vec{y})$

Then the joint pdf of the vector of functions is $g(\vec{y}) = |J|f(\vec{x})$

where J is the
Jacobian determinant: $J = \begin{vmatrix} \frac{\partial x_1}{\partial y_1} & \frac{\partial x_1}{\partial y_2} & \cdots & \frac{\partial x_1}{\partial y_n} \\ \frac{\partial x_2}{\partial y_1} & \frac{\partial x_2}{\partial y_2} & \cdots & \frac{\partial x_2}{\partial y_n} \\ \vdots & & & \vdots \\ & & \cdots & \frac{\partial x_n}{\partial y_n} \end{vmatrix}$

For e.g. $g_1(y_1)$ integrate $g(\vec{y})$ over the unwanted components.

Statistical Data Analysis

Lecture 2-2

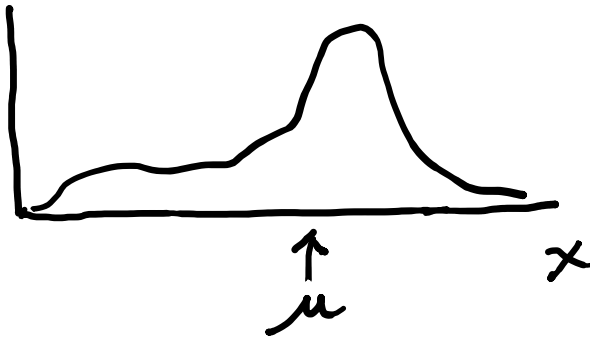
- Expectation values
- Covariance and correlation

Expectation values

Consider continuous r.v. x with pdf $f(x)$.

Define expectation (mean) value as $E[x] = \int x f(x) dx$

Notation (often): $E[x] = \mu \sim$ “centre of gravity” of pdf.



For discrete r.v.s, replace integral by sum: $E[x] = \sum_{x_i \in S} x_i P(x_i)$

For a function $y(x)$ with pdf $g(y)$,

$$E[y] = \int y g(y) dy = \int y(x) f(x) dx \quad (\text{equivalent})$$

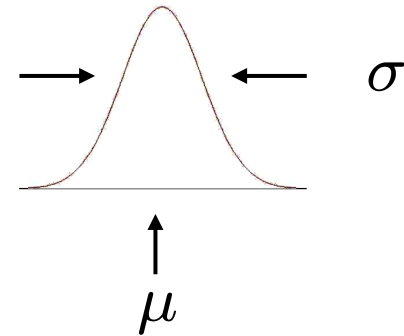
Variance, standard deviation

Variance: $V[x] = E[x^2] - \mu^2 = E[(x - \mu)^2]$

Notation: $V[x] = \sigma^2$

Standard deviation: $\sigma = \sqrt{\sigma^2}$

$\sigma \sim$ width of pdf, same units as x .



Relation between σ and other measures of width, e.g., Full Width at Half Max (FWHM) depend on the pdf, e.g., $\text{FWHM} = 2.35\sigma$ for Gaussian.

Moments of a distribution

Can characterize shape of a pdf with its moments:

$$E[x^n] = \int x^n f(x) dx \equiv \mu'_n$$

= n th algebraic moment, e.g., $\mu'_1 = \mu$ (the mean)

$$E[(x - E[x])^n] = \int (x - \mu)^n f(x) dx \equiv \mu_n$$

= n th central moment, e.g., $\mu_2 = \sigma^2$

Zeroth moment = 1 (always). Higher moments may not exist.

3rd moment is a measure of “skewness”: $\tilde{\mu}^3 = E \left[\left(\frac{x - \mu}{\sigma} \right)^3 \right]$


Expectation values – multivariate case

Suppose we have a 2-D joint pdf $f(x,y)$.

By “expectation value of x ” we mean:

$$E[x] = \int \int x f(x, y) dx dy = \int x f_x(x) dx = \mu_x$$

Sometimes it is useful to consider e.g. the conditional expectation value of x given y ,

$$E[x|y] = \int x f(x|y) dx$$

$$\frac{f(x, y)}{f_y(y)}$$

Covariance and correlation

Define covariance $\text{cov}[x,y]$ (also use matrix notation V_{xy}) as

$$\text{COV}[x, y] = E[xy] - \mu_x \mu_y = E[(x - \mu_x)(y - \mu_y)]$$

Correlation coefficient (dimensionless) defined as

$$\rho_{xy} = \frac{\text{COV}[x, y]}{\sigma_x \sigma_y} \quad \text{Can show } -1 \leq \rho \leq 1.$$

If x, y , independent, i.e., $f(x, y) = f_x(x)f_y(y)$

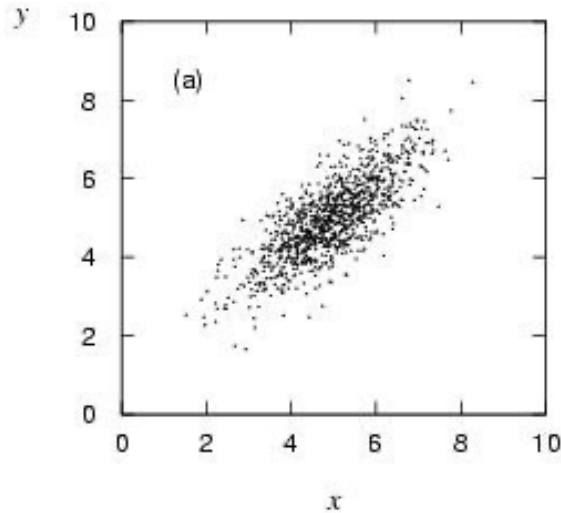
$$E[xy] = \int \int xy f(x, y) dx dy = \mu_x \mu_y$$

$$\rightarrow \text{COV}[x, y] = 0$$

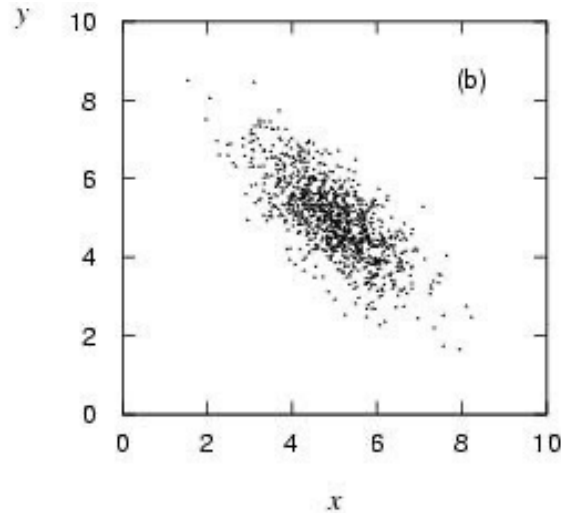
N.B. converse not always true.

Correlation (cont.)

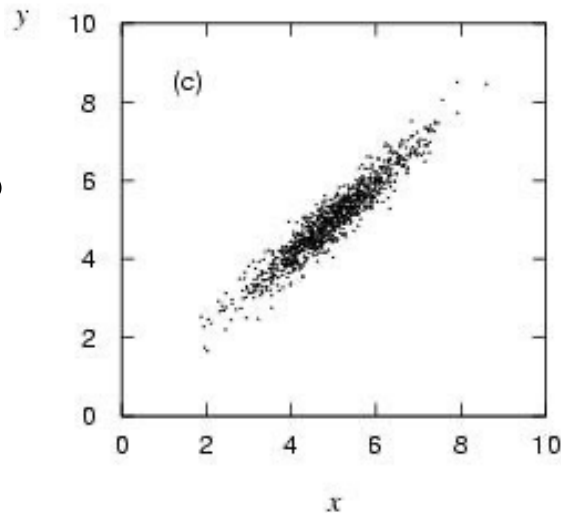
$$\rho = 0.75$$



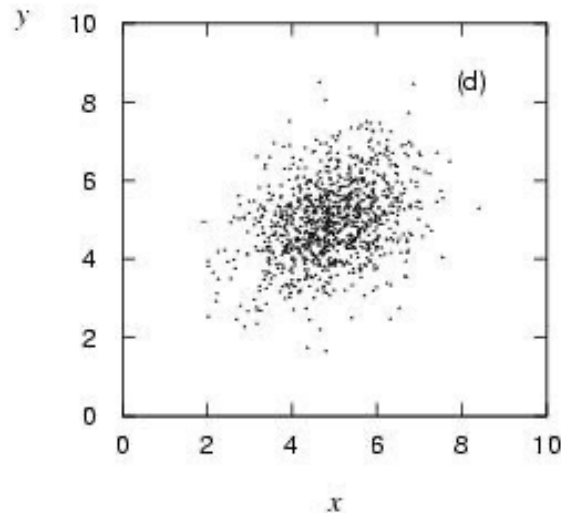
$$\rho = -0.75$$



$$\rho = 0.95$$



$$\rho = 0.25$$



Covariance matrix

Suppose we have a set of n random variables, say, x_1, \dots, x_n .

We can write the covariance of each pair as an $n \times n$ matrix:

$$V_{ij} = \text{COV}[x_i, x_j] = \rho_{ij} \sigma_i \sigma_j$$

$$V = \begin{pmatrix} \sigma_1^2 & \rho_{12}\sigma_1\sigma_2 & \dots & \rho_{1n}\sigma_1\sigma_n \\ \rho_{21}\sigma_2\sigma_1 & \sigma_2^2 & \dots & \rho_{2n}\sigma_2\sigma_n \\ \vdots & & \ddots & \vdots \\ \rho_{n1}\sigma_n\sigma_1 & \rho_{n2}\sigma_n\sigma_2 & \dots & \sigma_n^2 \end{pmatrix}$$

Covariance matrix is:

symmetric,

diagonal = variances,

positive semi-definite:

$$z^T V z \geq 0 \text{ for all } z \in \mathbb{R}^n$$

Correlation matrix

Closely related to the covariance matrix is the $n \times n$ matrix of correlation coefficients:

$$\rho_{ij} = \frac{\text{COV}[x_i, x_j]}{\sigma_i \sigma_j}$$

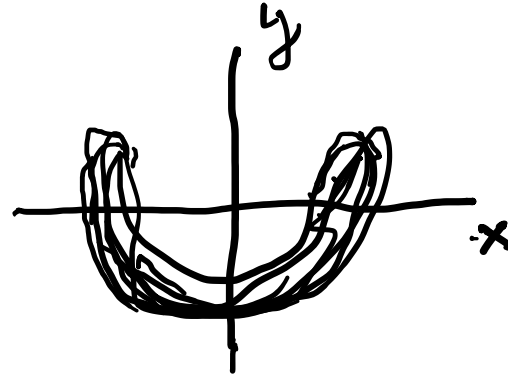
$$\rho = \begin{pmatrix} 1 & \rho_{12} & \dots & \rho_{1n} \\ \rho_{21} & 1 & \dots & \rho_{2n} \\ \vdots & & \ddots & \vdots \\ \rho_{n1} & \rho_{n2} & \dots & 1 \end{pmatrix}$$

By construction, diagonal elements are $\rho_{ii} = 1$

Correlation vs. independence

Consider a joint pdf such as:

I.e. here $f(-x, y) = f(x, y)$



Because of the symmetry, we have $E[x] = 0$ and also

$$E[xy] = \int_{-\infty}^{\infty} \int_{-\infty}^0 xy f(x, y) dx dy + \int_{-\infty}^{\infty} \int_0^{\infty} xy f(x, y) dx dy = 0$$

and so $\rho = 0$, the two variables x and y are uncorrelated.

But $f(y|x)$ clearly depends on x , so x and y are not independent.

Uncorrelated: the joint density of x and y is not tilted.

Independent: imposing x does not affect conditional pdf of y .

Statistical Data Analysis

Lecture 2-3

- Error propagation
 - goal: find variance of a function
 - derivation of formula
 - limitations
 - special cases

Error propagation

Suppose we measure a set of values $\vec{x} = (x_1, \dots, x_n)$
and we have the covariances $V_{ij} = \text{COV}[x_i, x_j]$
which quantify the measurement errors in the x_i .

Now consider a function $y(\vec{x})$.

What is the variance of $y(\vec{x})$?

The hard way: use joint pdf $f(\vec{x})$ to find the pdf $g(y)$,
then from $g(y)$ find $V[y] = E[y^2] - (E[y])^2$.

Often not practical, $f(\vec{x})$ may not even be fully known.

Error propagation formula (1)

Suppose we had $\vec{\mu} = E[\vec{x}]$

in practice only estimates given by the measured \vec{x}

Expand $y(\vec{x})$ to 1st order in a Taylor series about $\vec{\mu}$

$$y(\vec{x}) \approx y(\vec{\mu}) + \sum_{i=1}^n \left[\frac{\partial y}{\partial x_i} \right]_{\vec{x}=\vec{\mu}} (x_i - \mu_i)$$

To find $V[y]$ we need $E[y^2]$ and $E[y]$.

$$E[y(\vec{x})] \approx y(\vec{\mu}) \quad \text{since} \quad E[x_i - \mu_i] = 0$$

Error propagation formula (2)

$$\begin{aligned} E[y^2(\vec{x})] &\approx y^2(\vec{\mu}) + 2y(\vec{\mu}) \sum_{i=1}^n \left[\frac{\partial y}{\partial x_i} \right]_{\vec{x}=\vec{\mu}} E[x_i - \mu_i] \\ &\quad + E \left[\left(\sum_{i=1}^n \left[\frac{\partial y}{\partial x_i} \right]_{\vec{x}=\vec{\mu}} (x_i - \mu_i) \right) \left(\sum_{j=1}^n \left[\frac{\partial y}{\partial x_j} \right]_{\vec{x}=\vec{\mu}} (x_j - \mu_j) \right) \right] \\ &= y^2(\vec{\mu}) + \sum_{i,j=1}^n \left[\frac{\partial y}{\partial x_i} \frac{\partial y}{\partial x_j} \right]_{\vec{x}=\vec{\mu}} V_{ij} \end{aligned}$$

Putting the ingredients together gives the variance of $y(\vec{x})$

$$\sigma_y^2 \approx \sum_{i,j=1}^n \left[\frac{\partial y}{\partial x_i} \frac{\partial y}{\partial x_j} \right]_{\vec{x}=\vec{\mu}} V_{ij}$$

Error propagation formula (3)

If the x_i are uncorrelated, i.e., $V_{ij} = \sigma_i^2 \delta_{ij}$, then this becomes

$$\sigma_y^2 \approx \sum_{i=1}^n \left[\frac{\partial y}{\partial x_i} \right]_{\vec{x}=\vec{\mu}}^2 \sigma_i^2$$

Similar for a set of m functions $\vec{y}(\vec{x}) = (y_1(\vec{x}), \dots, y_m(\vec{x}))$

$$U_{kl} = \text{COV}[y_k, y_l] \approx \sum_{i,j=1}^n \left[\frac{\partial y_k}{\partial x_i} \frac{\partial y_l}{\partial x_j} \right]_{\vec{x}=\vec{\mu}} V_{ij}$$

or in matrix notation $U = A V A^T$, where

$$A_{ij} = \left[\frac{\partial y_i}{\partial x_j} \right]_{\vec{x}=\vec{\mu}}$$

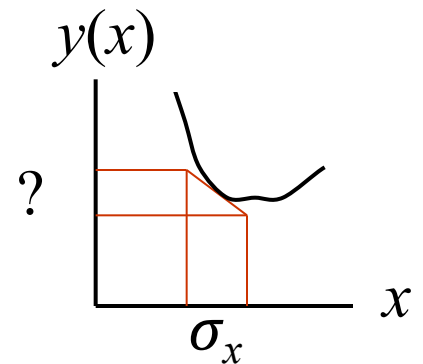
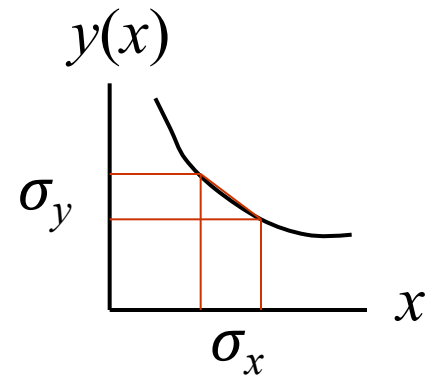
Error propagation – limitations

The ‘error propagation’ formulae tell us the covariances of a set of functions

$\vec{y}(\vec{x}) = (y_1(\vec{x}), \dots, y_m(\vec{x}))$ terms of the covariances of the original variables.

Limitations: exact only if $\vec{y}(\vec{x})$ linear.

Approximation breaks down if function nonlinear over a region comparable in size to the σ_i .



N.B. We have said nothing about the exact pdf of the x_i , e.g., it doesn't have to be Gaussian.

Error propagation – special cases

$$y = x_1 + x_2 \rightarrow \sigma_y^2 = \sigma_1^2 + \sigma_2^2 + 2\text{cov}[x_1, x_2]$$

$$y = x_1 x_2 \rightarrow \frac{\sigma_y^2}{y^2} = \frac{\sigma_1^2}{x_1^2} + \frac{\sigma_2^2}{x_2^2} + 2 \frac{\text{cov}[x_1, x_2]}{x_1 x_2}$$

That is, if the x_i are uncorrelated:

add errors quadratically for the sum (or difference),

add relative errors quadratically for product (or ratio).



But correlations can change this completely...

Error propagation – special cases (2)

Consider $y = x_1 - x_2$ with

$$\mu_1 = \mu_2 = 10, \quad \sigma_1 = \sigma_2 = 1, \quad \rho = \frac{\text{COV}[x_1, x_2]}{\sigma_1 \sigma_2} = 0.$$

$$V[y] = 1^2 + 1^2 = 2, \rightarrow \sigma_y = 1.4$$

Now suppose $\rho = 1$. Then

$$V[y] = 1^2 + 1^2 - 2 = 0, \rightarrow \sigma_y = 0$$

i.e. for 100% correlation, error in difference $\rightarrow 0$.

Statistical Data Analysis

Lectures 2-4 through 3-2 intro

We will now run through a short catalog of probability functions and pdfs.

For each (usually) show expectation value, variance, a plot and discuss some properties and applications.

See also chapter on probability from pdg.lbl.gov

For a more complete catalogue see e.g. the handbook on statistical distributions by Christian Walck from staff.fysik.su.se/~walck/suf9601.pdf

Some distributions

<u>Distribution/pdf</u>	<u>Example use in Particle Physics</u>
Binomial	Branching ratio
Multinomial	Histogram with fixed N
Poisson	Number of events found
Uniform	Monte Carlo method
Exponential	Decay time
Gaussian	Measurement error
Chi-square	Goodness-of-fit
Cauchy	Mass of resonance
Landau	Ionization energy loss
Beta	Prior pdf for efficiency
Gamma	Sum of exponential variables
Student's t	Resolution function with adjustable tails

Statistical Data Analysis

Lecture 2-4

- Discrete probability distributions
 - binomial
 - multinomial
 - Poisson

Binomial distribution

Consider N independent experiments (Bernoulli trials):

outcome of each is ‘success’ or ‘failure’,
probability of success on any given trial is p .

Define discrete r.v. n = number of successes ($0 \leq n \leq N$).

Probability of a specific outcome (in order), e.g. ‘ssfsf’ is

$$pp(1-p)p(1-p) = p^n(1-p)^{N-n}$$

But order not important; there are $\frac{N!}{n!(N-n)!}$


ways (permutations) to get n successes in N trials, total probability for n is sum of probabilities for each permutation.

Binomial distribution (2)

The binomial distribution is therefore

$$f(n; N, p) = \frac{N!}{n!(N - n)!} p^n (1 - p)^{N - n}$$

random variable parameters



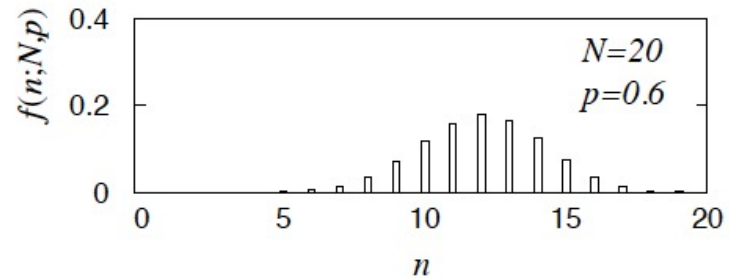
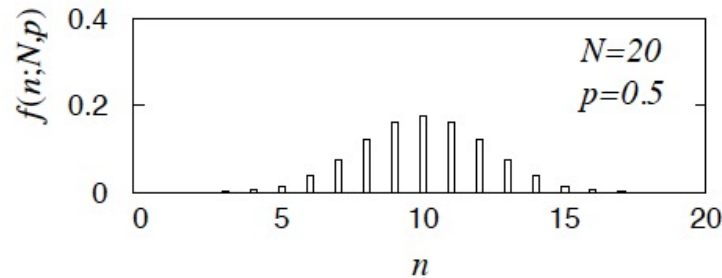
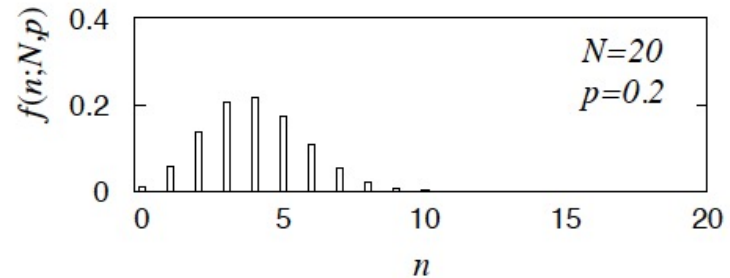
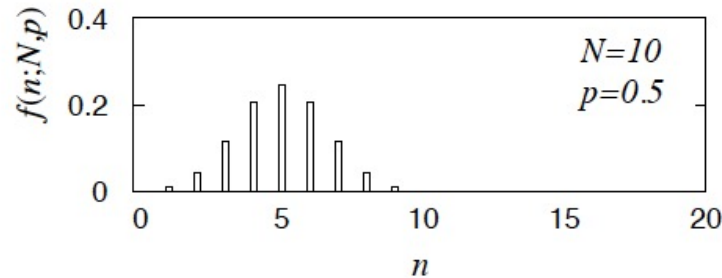
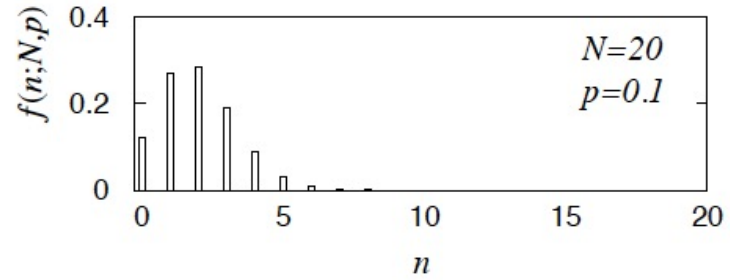
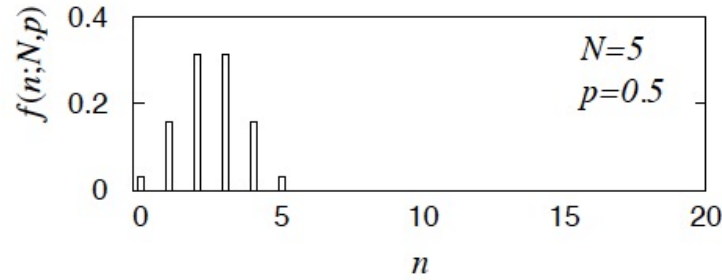
For the expectation value and variance we find:

$$E[n] = \sum_{n=0}^N n f(n; N, p) = Np$$

$$V[n] = E[n^2] - (E[n])^2 = Np(1 - p)$$

Binomial distribution (3)

Binomial distribution for several values of the parameters:



Example: observe N decays of W^\pm , the number n of which are $W \rightarrow \mu\nu$ is a binomial r.v., p = branching ratio.

Multinomial distribution

Like binomial but now m outcomes instead of two, probabilities are

$$\vec{p} = (p_1, \dots, p_m), \quad \text{with} \quad \sum_{i=1}^m p_i = 1.$$

For N trials we want the probability to obtain:

n_1 of outcome 1,
 n_2 of outcome 2,
 \vdots
 n_m of outcome m .

This is the multinomial distribution for $\vec{n} = (n_1, \dots, n_m)$

$$f(\vec{n}; N, \vec{p}) = \frac{N!}{n_1! n_2! \dots n_m!} p_1^{n_1} p_2^{n_2} \dots p_m^{n_m}$$

Multinomial distribution (2)

Now consider outcome i as ‘success’, all others as ‘failure’.

→ all n_i individually binomial with parameters N, p_i

$$E[n_i] = Np_i, \quad V[n_i] = Np_i(1 - p_i) \quad \text{for all } i$$

One can also find the covariance to be

$$V_{ij} = Np_i(\delta_{ij} - p_j)$$

Example: $\vec{n} = (n_1, \dots, n_m)$ represents a histogram with m bins, N total entries, all entries independent.

Poisson distribution

Consider binomial n in the limit

$$N \rightarrow \infty, \quad p \rightarrow 0, \quad E[n] = Np \rightarrow \nu .$$

→ n follows the Poisson distribution:

$$f(n; \nu) = \frac{\nu^n}{n!} e^{-\nu} \quad (n \geq 0)$$

$$E[n] = \nu, \quad V[n] = \nu .$$

Example: number of scattering events n with cross section σ found for a fixed integrated luminosity, with $\nu = \sigma \int L dt$.

