


Statistical Data Analysis: Lecture 3

- 1 Probability, Bayes' theorem
- 2 Random variables and probability densities
-  3 **Expectation values, error propagation**
- 4 Catalogue of pdfs
- 5 The Monte Carlo method
- 6 Statistical tests: general concepts
- 7 Test statistics, multivariate methods
- 8 Goodness-of-fit tests
- 9 Parameter estimation, maximum likelihood
- 10 More maximum likelihood
- 11 Method of least squares
- 12 Interval estimation, setting limits
- 13 Nuisance parameters, systematic uncertainties
- 14 Examples of Bayesian approach

Expectation values

Consider continuous r.v. x with pdf $f(x)$.

Define expectation (mean) value as $E[x] = \int x f(x) dx$

Notation (often): $E[x] = \mu \sim$ “centre of gravity” of pdf.

For a function $y(x)$ with pdf $g(y)$,

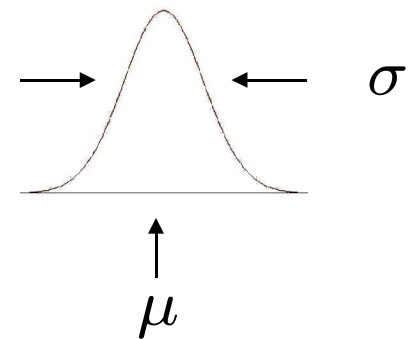
$$E[y] = \int y g(y) dy = \int y(x) f(x) dx \quad (\text{equivalent})$$

Variance: $V[x] = E[x^2] - \mu^2 = E[(x - \mu)^2]$

Notation: $V[x] = \sigma^2$

Standard deviation: $\sigma = \sqrt{\sigma^2}$

$\sigma \sim$ width of pdf, same units as x .



Covariance and correlation

Define covariance $\text{cov}[x,y]$ (also use matrix notation V_{xy}) as

$$\text{COV}[x, y] = E[xy] - \mu_x\mu_y = E[(x - \mu_x)(y - \mu_y)]$$

Correlation coefficient (dimensionless) defined as

$$\rho_{xy} = \frac{\text{COV}[x, y]}{\sigma_x\sigma_y}$$

If x, y , independent, i.e., $f(x, y) = f_x(x)f_y(y)$, then

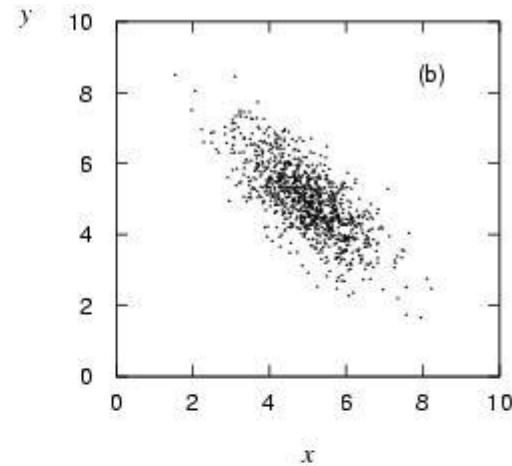
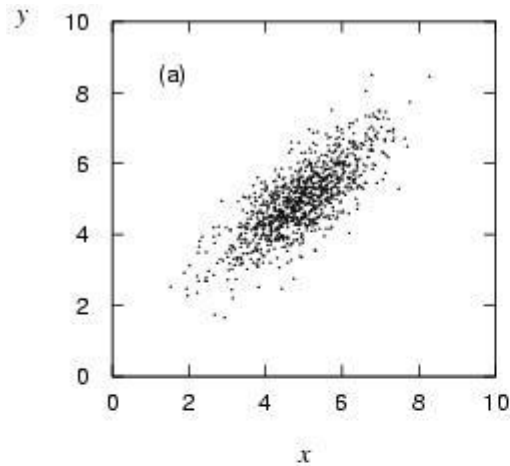
$$E[xy] = \int \int xy f(x, y) dx dy = \mu_x\mu_y$$

→ $\text{COV}[x, y] = 0$ x and y , ‘uncorrelated’

N.B. converse not always true.

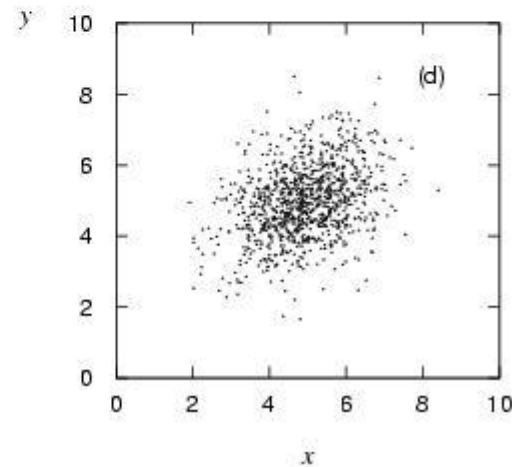
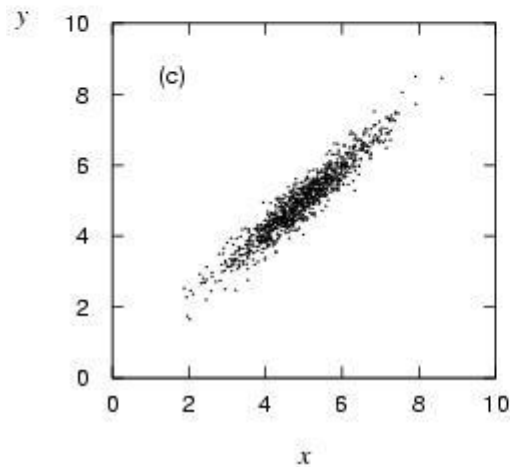
Correlation (cont.)

$$\rho = 0.75$$



$$\rho = -0.75$$

$$\rho = 0.95$$



$$\rho = 0.25$$

Error propagation

Suppose we measure a set of values $\vec{x} = (x_1, \dots, x_n)$

and we have the covariances $V_{ij} = \text{COV}[x_i, x_j]$

which quantify the measurement errors in the x_i .

Now consider a function $y(\vec{x})$.

What is the variance of $y(\vec{x})$?

The hard way: use joint pdf $f(\vec{x})$ to find the pdf $g(y)$,

then from $g(y)$ find $V[y] = E[y^2] - (E[y])^2$.

Often not practical, $f(\vec{x})$ may not even be fully known.

Error propagation (2)

Suppose we had $\vec{\mu} = E[\vec{x}]$

in practice only estimates given by the measured \vec{x}

Expand $y(\vec{x})$ to 1st order in a Taylor series about $\vec{\mu}$

$$y(\vec{x}) \approx y(\vec{\mu}) + \sum_{i=1}^n \left[\frac{\partial y}{\partial x_i} \right]_{\vec{x}=\vec{\mu}} (x_i - \mu_i)$$

To find $V[y]$ we need $E[y^2]$ and $E[y]$.

$$E[y(\vec{x})] \approx y(\vec{\mu}) \quad \text{since} \quad E[x_i - \mu_i] = 0$$

Error propagation (3)

$$\begin{aligned} E[y^2(\vec{x})] &\approx y^2(\vec{\mu}) + 2y(\vec{\mu}) \sum_{i=1}^n \left[\frac{\partial y}{\partial x_i} \right]_{\vec{x}=\vec{\mu}} E[x_i - \mu_i] \\ &\quad + E \left[\left(\sum_{i=1}^n \left[\frac{\partial y}{\partial x_i} \right]_{\vec{x}=\vec{\mu}} (x_i - \mu_i) \right) \left(\sum_{j=1}^n \left[\frac{\partial y}{\partial x_j} \right]_{\vec{x}=\vec{\mu}} (x_j - \mu_j) \right) \right] \\ &= y^2(\vec{\mu}) + \sum_{i,j=1}^n \left[\frac{\partial y}{\partial x_i} \frac{\partial y}{\partial x_j} \right]_{\vec{x}=\vec{\mu}} V_{ij} \end{aligned}$$

Putting the ingredients together gives the variance of $y(\vec{x})$

$$\sigma_y^2 \approx \sum_{i,j=1}^n \left[\frac{\partial y}{\partial x_i} \frac{\partial y}{\partial x_j} \right]_{\vec{x}=\vec{\mu}} V_{ij}$$

Error propagation (4)

If the x_i are uncorrelated, i.e., $V_{ij} = \sigma_i^2 \delta_{ij}$, then this becomes

$$\sigma_y^2 \approx \sum_{i=1}^n \left[\frac{\partial y}{\partial x_i} \right]_{\vec{x}=\vec{\mu}}^2 \sigma_i^2$$

Similar for a set of m functions $\vec{y}(\vec{x}) = (y_1(\vec{x}), \dots, y_m(\vec{x}))$

$$U_{kl} = \text{COV}[y_k, y_l] \approx \sum_{i,j=1}^n \left[\frac{\partial y_k}{\partial x_i} \frac{\partial y_l}{\partial x_j} \right]_{\vec{x}=\vec{\mu}} V_{ij}$$

or in matrix notation $U = AVA^T$, where

$$A_{ij} = \left[\frac{\partial y_i}{\partial x_j} \right]_{\vec{x}=\vec{\mu}}$$

Error propagation (5)

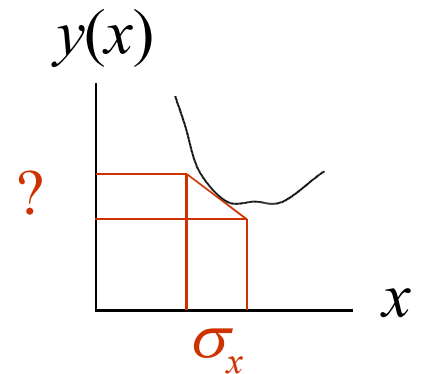
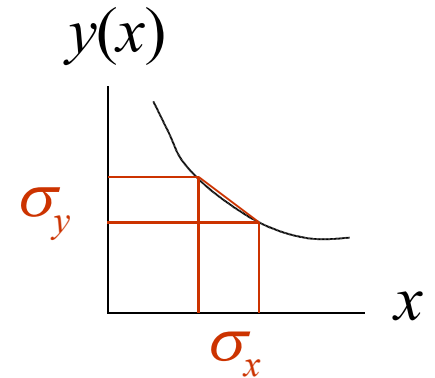
The ‘error propagation’ formulae tell us the covariances of a set of functions

$\vec{y}(\vec{x}) = (y_1(\vec{x}), \dots, y_m(\vec{x}))$ in terms of the covariances of the original variables.

Limitations: exact only if $\vec{y}(\vec{x})$ linear.

Approximation breaks down if function nonlinear over a region comparable in size to the σ_i .

N.B. We have said nothing about the exact pdf of the x_i , e.g., it doesn’t have to be Gaussian.



Error propagation – special cases

$$y = x_1 + x_2 \rightarrow \sigma_y^2 = \sigma_1^2 + \sigma_2^2 + 2\text{COV}[x_1, x_2]$$

$$y = x_1 x_2 \rightarrow \frac{\sigma_y^2}{y^2} = \frac{\sigma_1^2}{x_1^2} + \frac{\sigma_2^2}{x_2^2} + 2 \frac{\text{COV}[x_1, x_2]}{x_1 x_2}$$

That is, if the x_i are uncorrelated:

add errors quadratically for the sum (or difference),

add relative errors quadratically for product (or ratio).



But correlations can change this completely...

Error propagation – special cases (2)

Consider $y = x_1 - x_2$ with

$$\mu_1 = \mu_2 = 10, \quad \sigma_1 = \sigma_2 = 1, \quad \rho = \frac{\text{COV}[x_1, x_2]}{\sigma_1 \sigma_2} = 0.$$

$$V[y] = 1^2 + 1^2 = 2, \rightarrow \sigma_y = 1.4$$

Now suppose $\rho = 1$. Then

$$V[y] = 1^2 + 1^2 - 2 = 0, \rightarrow \sigma_y = 0$$

i.e. for 100% correlation, error in difference $\rightarrow 0$.

Wrapping up lecture 3

We know how to describe a pdf using

expectation values (mean, variance),
covariance, correlation, ...

Given a function of a random variable, we know how
to find the variance of the function using error propagation.

also for covariance matrix in multivariate case;
based on linear approximation.