#### Note on Blobel's Unfolding Method

#### 1 Introduction and notation

The purpose of this note is to clarify the prescription used by Blobel [1] to determine the regularization parameter in unfolding. This involves a succession of transformations of variables such that the new variables have a diagonal covariance matrix. The procedure explained in [1] differs in certain respects from that implemented in the program RUN [2]; the algorithm of RUN is explained in Section 5.

The notation used here is that of *Statistical Data Analysis* [3]. The observed histogram  $\mathbf{n} = (n_1, \ldots, n_N)$  is regarded as an N-dimensional random vector with expectation values  $\boldsymbol{\nu} = E[\mathbf{n}]$ . These are related to an M-dimensional "true" histogram  $\boldsymbol{\mu} = (\mu_1, \ldots, \mu_M)$  by

$$\boldsymbol{\nu} = R\boldsymbol{\mu} + \boldsymbol{\beta},\tag{1}$$

where R is the response matrix and  $\boldsymbol{\beta}$  is a vector of expected background values. Both R and  $\boldsymbol{\beta}$  are assumed known.

The goal is to construct estimators  $\hat{\boldsymbol{\mu}}$  for the true parameters  $\boldsymbol{\mu}$ . In regularized unfolding, these are found by minimizing

$$\Phi(\boldsymbol{\mu}) = \chi^{2}(\boldsymbol{\mu}) + \tau \boldsymbol{\mu}^{T} G \boldsymbol{\mu} 
= (\mathbf{n} - \boldsymbol{\beta} - R \boldsymbol{\mu})^{T} V^{-1} (\mathbf{n} - \boldsymbol{\beta} - R \boldsymbol{\mu}) + \tau \boldsymbol{\mu}^{T} G \boldsymbol{\mu}.$$
(2)

Here the covariance matrix of the data  $V_{ij} = \cos[n_i, n_j]$  is assumed to be known and  $\tau$  is the regularization parameter. The symmetric  $M \times M$  matrix G can be chosen so that the regularization function function  $\mu^T G \mu$  corresponds to the average curvature of the solution (see [1, 3]). Here,  $\tau$  is attached to the regularization function rather than the log-likelihood, as done in [3].

## 2 The estimators $\hat{\mu}$ for a given $\tau$

For a given value of the regularization parameter  $\tau$ , the estimators  $\hat{\boldsymbol{\mu}}$  are found by setting the derivatives of  $\Phi$  with respect to the  $\mu_i$  equal to zero,

$$\nabla \Phi(\boldsymbol{\mu}) = -R^T V^{-1} (\mathbf{n} - \boldsymbol{\beta} - R\boldsymbol{\mu}) + \tau G \boldsymbol{\mu} = 0.$$
 (3)

The solution is

$$\hat{\boldsymbol{\mu}} = (R^T V^{-1} R + \tau G)^{-1} R^T V^{-1} (\mathbf{n} - \boldsymbol{\beta}) \equiv L(\mathbf{n} - \boldsymbol{\beta}). \tag{4}$$

Since the estimators are linear functions of the data  $\mathbf{n}$ , the covariance matrix  $U_{ij} = \cos[\hat{\mu}_i, \hat{\mu}_j]$  is found by error propagation to be

$$U = LVL^T. (5)$$

If one considers the special case  $\tau = 0$  (the unregularized solution), equation (4) reduces to  $\hat{\boldsymbol{\mu}} = R^{-1}(\mathbf{n} - \boldsymbol{\beta})$ ; this solution will be denoted by  $\hat{\boldsymbol{\mu}}_0$ .

## 3 Transforming $\mu$

Consider the function  $\Phi(\boldsymbol{\mu})$ ,

$$\Phi(\boldsymbol{\mu}) = (\mathbf{n} - \boldsymbol{\beta} - R\boldsymbol{\mu})^T V^{-1} (\mathbf{n} - \boldsymbol{\beta} - R\boldsymbol{\mu}) + \tau \boldsymbol{\mu}^T G \boldsymbol{\mu} 
= (\mathbf{n} - \boldsymbol{\beta})^T (\mathbf{n} - \boldsymbol{\beta}) - 2(\mathbf{n} - \boldsymbol{\beta})^T V^{-1} R \boldsymbol{\mu} + \boldsymbol{\mu}^T R^T V^{-1} R \boldsymbol{\mu} + \tau \boldsymbol{\mu}^T G \boldsymbol{\mu},$$
(6)

the minimum of which defines the regularized solution. In order to arrive at the prescription for determining  $\tau$ , one must carrying out three transformations on  $\mu$ . These are arranged such that the transformed quantities have a diagonal covariance matrix which reduces to the unit matrix for  $\tau = 0$ . The transformations are:

- (1) an orthogonal transformation,  $\mathbf{a} = A\boldsymbol{\mu}$ , such that the quadratic term  $\boldsymbol{\mu}^T R^T V^{-1} R\boldsymbol{\mu}$  in (6) takes on the form  $\mathbf{a}^T B^2 \mathbf{a}$  with  $B^2$  a diagonal matrix;
- (2) a rescaling,  $\mathbf{b} = B\mathbf{a}$ , such that the quadratic term becomes  $\mathbf{b}^T\mathbf{b}$ , i.e.  $B_{ii} = \sqrt{(B^2)_{ii}}$  and  $B_{ij} = 0$  for  $i \neq j$ ;
- (3) an orthogonal transformation,  $\mathbf{c} = C\mathbf{b}$ , such that the regularization term in (6) can be expressed as  $\tau \mathbf{c}^T D \mathbf{c}$  with D a diagonal matrix.

The columns of A are given by the eigenvectors of  $R^TV^{-1}R$ , the diagonal matrix B is defined by  $B^2 = AR^TV^{-1}RA^T$ , and the columns of C are given by the eigenvectors of  $B^{-1}AGA^TB^{-1}$ . Note that one has  $\mathbf{b}^T\mathbf{b} = \mathbf{c}^T\mathbf{c}$ , since the transformation  $\mathbf{c} = C\mathbf{b}$  is orthogonal. The important ingredient here is the matrix D, which is given by

$$D = CB^{-1}AGA^{T}B^{-1}C^{T}. (7)$$

After transforming to  $\mathbf{c} = CBA\boldsymbol{\mu}$ , equation (6) becomes

$$\Phi(\mathbf{c}) = (\mathbf{n} - \boldsymbol{\beta})^T (\mathbf{n} - \boldsymbol{\beta}) - 2(\mathbf{n} - \boldsymbol{\beta})^T V^{-1} R A^T B^{-1} C^T \mathbf{c} + \mathbf{c}^T \mathbf{c} + \tau \mathbf{c}^T D \mathbf{c}.$$
 (8)

The solution is found by setting the derivatives of  $\Phi$  with respect to  $c_i$  equal to zero,

$$\nabla \Phi(\mathbf{c}) = -2CB^{-1}AR^TV^{-1}(\mathbf{n} - \boldsymbol{\beta}) + 2\mathbf{c} + 2\tau D\mathbf{c} = 0.$$
 (9)

This gives

$$\hat{\mathbf{c}} = (1 + \tau D)^{-1} C B^{-1} A R^T V^{-1} (\mathbf{n} - \boldsymbol{\beta})$$

$$= (1 + \tau D)^{-1} \hat{\mathbf{c}}_0.$$
(10)

where  $\hat{\mathbf{c}}_0$  is the unregularized solution. The covariance matrix  $W_{ij} = \cos[\hat{c}_i, \hat{c}_j]$  reduces to the simple diagonal form

$$W = \left[ (1+\tau D)^{-1}CB^{-1}AR^{T}V^{-1} \right] V \left[ (1+\tau D)^{-1}CB^{-1}AR^{T}V^{-1} \right]^{T}$$

$$= (1+\tau D)^{-2}. \tag{11}$$

Note that the components of  $\hat{\mathbf{c}}$  are uncorrelated, since D, and hence also W, is diagonal, and that in particular one has W=1 for the unregularized solution ( $\tau=0$ ). The standard deviation of the *i*th component  $\hat{c}_i$  is

$$\sqrt{W_{ii}} = \frac{1}{1 + \tau D_{ii}}. (12)$$

# 4 The number of statistically significant components $M_0$ and the rule for determining $\tau$

In order to formulate the rule for determining  $\tau$ , one first needs to introduce the concept of the number of statistically significant components of the unregularized solution. The covariance matrix of  $\hat{\mathbf{c}}_0$  is the unit matrix. Therefore, the value of each component  $\hat{c}_{0i}$  tells how many standard deviations it is from zero. In [1] Blobel recommends a 95% confidence level corresponding to 1.96 standard deviations. Out of the M components, the number which satisfy

$$|\hat{c}_{0i}| \ge 1.96 \tag{13}$$

is called the number of statistically significant components,  $M_0$ .

For the unregularized estimators  $\hat{\mathbf{c}}_0$ , the sum of the absolute values of the standard deviations gives the number of components M. The idea for determining  $\tau$  for the regularized solution is to make the corresponding sum equal to the number of statistically significant components  $M_0$ . That is,  $\tau$  is defined by the relation

$$M_0 = \sum_{i=1}^{M} \sqrt{W_{ii}} = \sum_{i=1}^{M} \frac{1}{1 + \tau D_{ii}}.$$
 (14)

## 5 Implementation in RUN

The algorithm actually implemented in the most recent version of Blobel's program RUN [2] is somewhat different from that described above. First, the user is given the option to set by hand the number of statistically significant components  $M_0$  by means of the input keyword NRDF, which sets the variable NDF. If this is set to zero, then the program uses a default algorithm to determine  $M_0$ , which is, however, different from the algorithm described in the previous section.

If NDF is input as zero, then the program first determines a provisional value of  $\tau$  by solving

$$0 = \sum_{i=1}^{M} \left[ (\hat{c}_{i0}^{2} - \hat{c}_{i}^{2}) - 1 \right] \frac{3}{3 + \tau D_{ii}}$$

$$= \sum_{i=1}^{M} \left[ \frac{\hat{c}_{i0}^{2} (2\tau D_{ii} + \tau^{2} D_{ii}^{2})}{(1 + \tau D_{ii})^{2}} - 1 \right] \frac{3}{3 + \tau D_{ii}}.$$
(15)

This is done in the routine RSOLRT. According to the comments in the routine, the idea is that the difference  $\hat{c}_{i0}^2 - \hat{c}_i^2$  can be considered as the random noise, which should be one per bin. The terms are weighted by the factor  $3/(3 + \tau D_{ii})$  in order to suppress larger amplitudes.

This value of  $\tau$  is then used to compute a provisional (non-integer) number of degrees of freedom (called XDFR in RSOLRT),

$$x_0 = \sum_{i=1}^{M} \frac{1}{1 + \tau D_{ii}} \tag{16}$$

This is incremented by one and rounded down to the nearest integer to give  $M_0$ , which is then passed to the routine RSOLEQ. There, a new value of  $\tau$  is determined according to equation (14), as described in the previous section. The statistical test for determining  $M_0$  described in the previous section is not used.

One feature of the program as it stands is that the user may only choose an integer value for  $M_0$ , which leads to a discrete number of choices for  $\tau$ . One way to bypass this is insert something like

```
if ( set_tau ) then
  tau = user_tau
  goto 20
endif
```

in the beginning of the routine RSOLEQ. The logical variable set\_tau must be set equal to .true., and the real variable user\_tau set equal to whatever the user wants. These can be brought into RSOLEQ via a common block. For a starting value of  $\tau$ , the default suggested by RUN can be used. This procedure seems to work except for extreme cases where one requests a very small  $\tau$ ; here the program apparently recognizes this as an abnormal condition and returns a much smoother solution than it should. Reasonable variations of  $\tau$  about its preferred value seem, however, to work.

Another way of allowing for an adjustment of  $\tau$  would be to modify equation (15) to be

$$0 = \sum_{i=1}^{M} \left[ (\hat{c}_{i0}^2 - \hat{c}_i^2) - \gamma \right] \frac{3}{3 + \tau D_{ii}}.$$
 (17)

By adjusting  $\gamma$  higher or lower than its default value of unity, the average amount random noise  $\hat{c}_{i0}^2 - \hat{c}_i^2$  can be varied. This will result in a different value of  $x_0$ ; if this changes by enough to change  $M_0$  then a different  $\tau$  will result.

#### References

- [1] V. Blobel, Unfolding methods in high energy physics experiments, DESY 84-118 (1984); also in *Proceedings of the 1984 CERN School of Computing*, CERN 85-09 (1985).
- [2] V. Blobel, The RUN manual: regularized unfolding for high-energy physics experiments, OPAL Technical Note TN361, March 8, 1996.
- [3] G. Cowan, Statistical Data Analysis, Clarendon Press, Oxford (1998).